Laboratoire d'Annecy de Physique des Particules

Optimisation : Reduction

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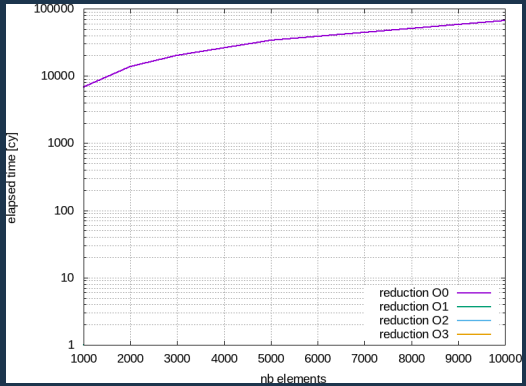
The Reduction (sum)

$$\alpha = \sum_{i=1}^{N} x_i$$

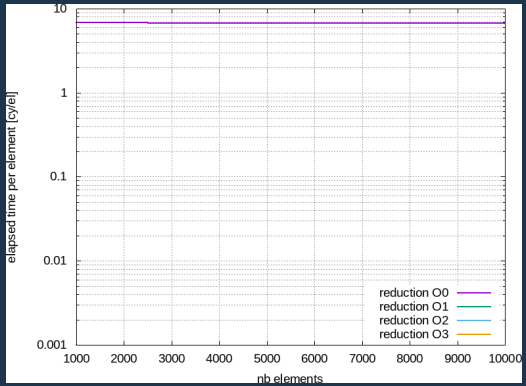

```
float reduction(const float * tabValue, long unsigned int nbElement){
»       float res(0.0f);
»       for(long unsigned int i(0lu); i < nbElement; ++i){
»       »       res += tabValue[i];
»       }
»       return res;
}
```

The reduction : first performances

Total Elapsed Time (cy)

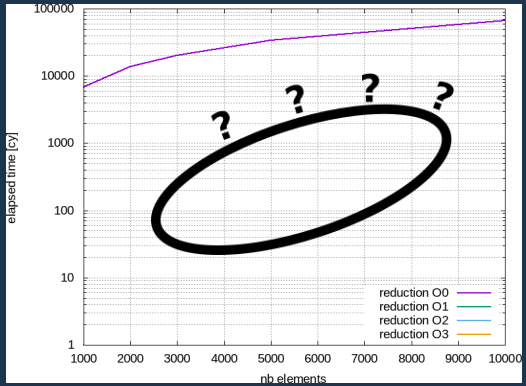


Elapsed Time per element (cy/el)

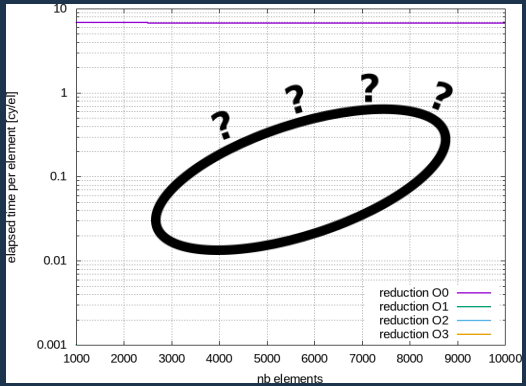


The reduction : first performances

Total Elapsed Time (cy)



Elapsed Time per element (cy/el)



The Performance : what is the issue ?

- Performances **-O0** : slow but reasonable
- Other performances (**-O1**, **-O2**, **-O3**, **-Ofast**) are too fast (non sence)

GCC is smart of guileful depending on the points of view.

- GCC noticed you **do not** use the result of the **reduction** function.
- The call to **reduction** is considered as dead code (or never called code).

To avoid that, you have to compile the **reduction** function in an other file.

Dead code for compiler

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Dead code for compiler

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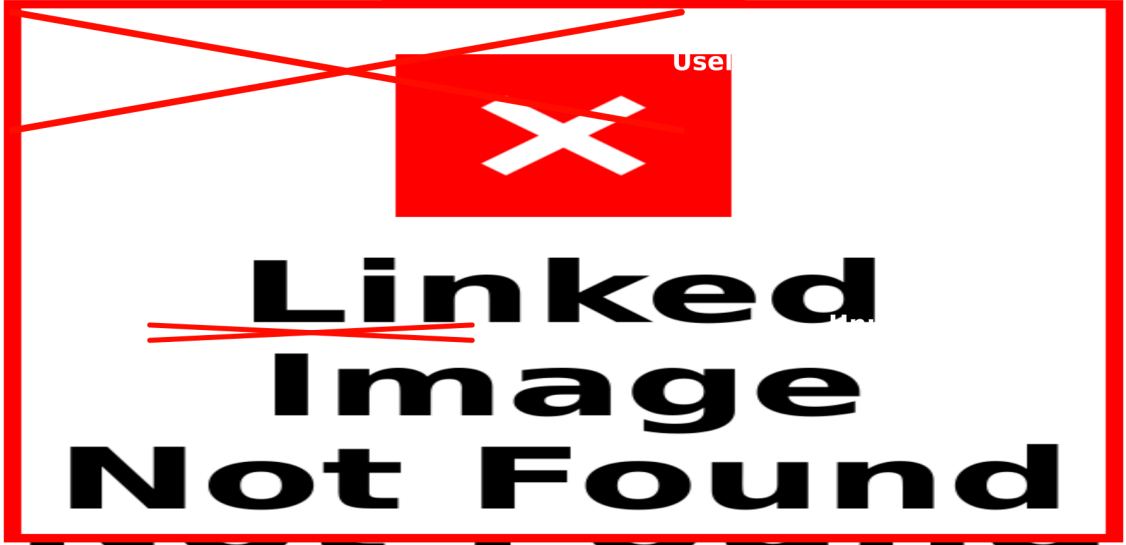
Dead code for compiler

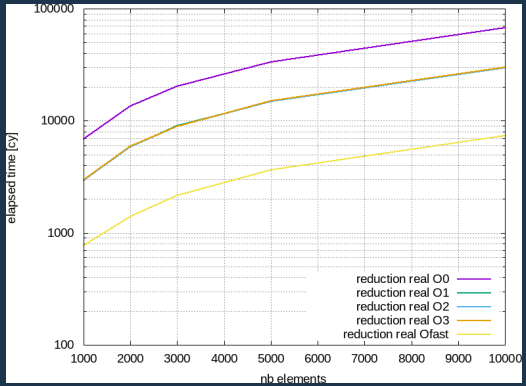


Dead code for compiler

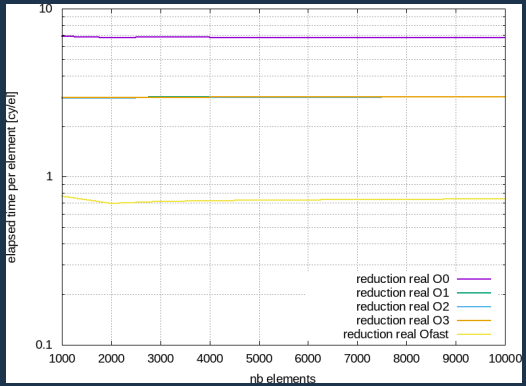
Dead code for compiler

The reduction : real performances

Total Elapsed Time (cy)



Elapsed Time per element (cy/el)



Modifications for vectorization

- Data alignement :
  - All the data to be aligned on vectorial registers size.
  - Change **new** or **malloc** to **memalign** or **posix_memalign**

You can use **asterics_malloc** to have LINUX/MAC compatibility (in **evaluateReduction**):

```
(float*)asterics_malloc(sizeof(float)*nbElement);
```

The __**restrict**__ keyword (arguments of **reduction** function):

```
const float * __restrict__ ptabValue
```

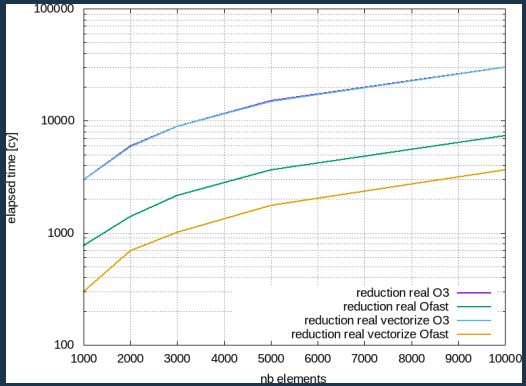
The __**builtin_assume_aligned** function call (in **reduction** function):

```
const float* tabValue = (const float*)__builtin_assume_aligned(ptabValue, VECTOR_ALIGNEMENT);
```

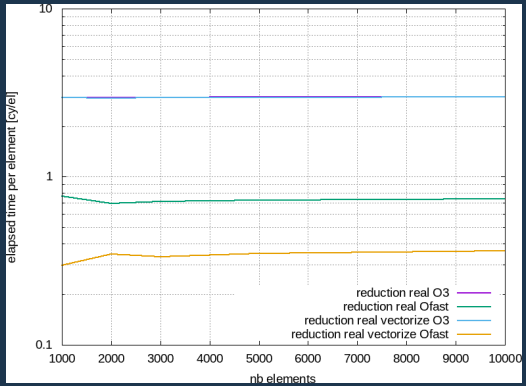
- The Compilation Options become :
  - **-O3 -ftree-vectorize -march=native -mtune=native -mavx2**

The reduction : vectorize performances

Total Elapsed Time (cy)

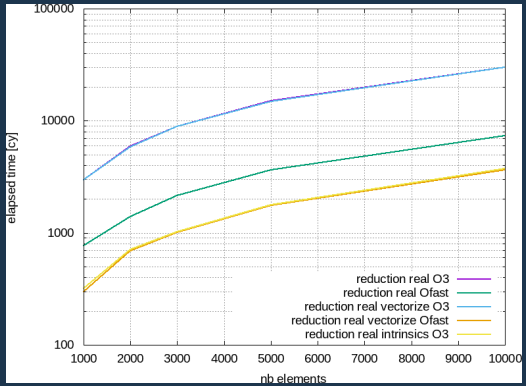


Elapsed Time per element (cy/el)

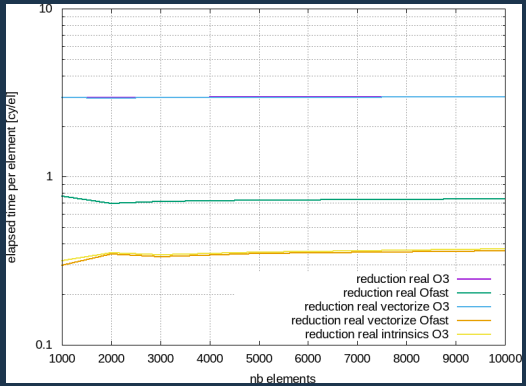


The reduction : intrinsics performances

Total Elapsed Time (cy)



Elapsed Time per element (cy/el)



Reduction optimisation

Reduction optimisation

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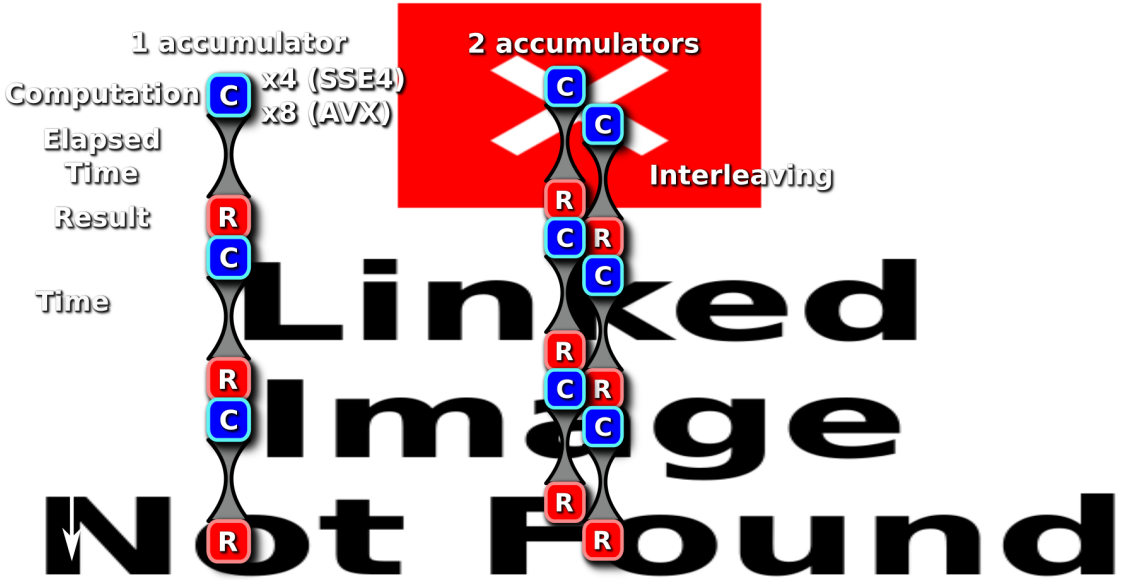
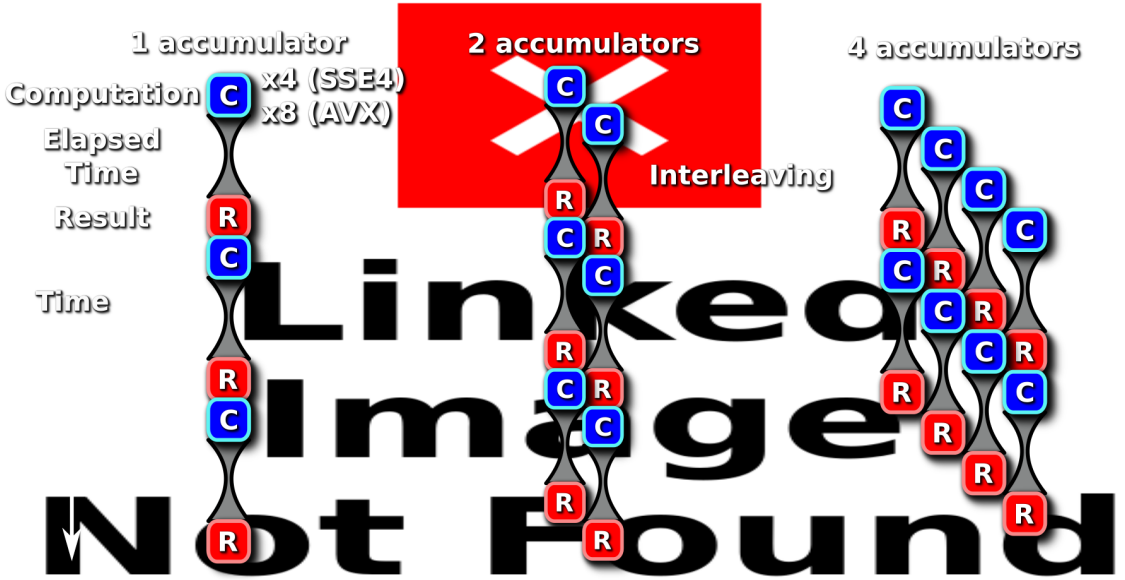
Reduction optimisation

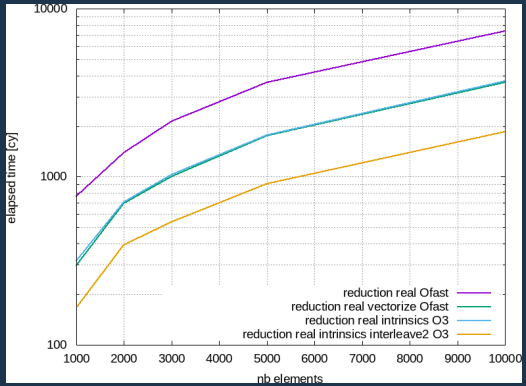


Reduction optimisation

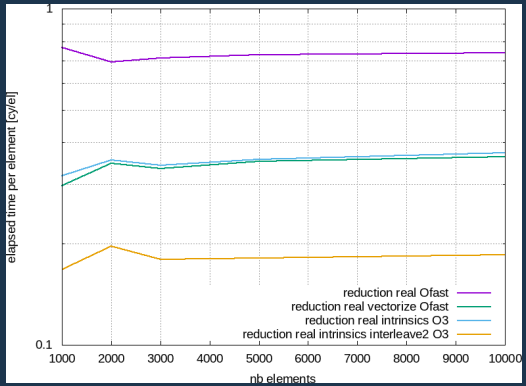


The reduction : intrinsics interleaved 2

Total Elapsed Time (cy)

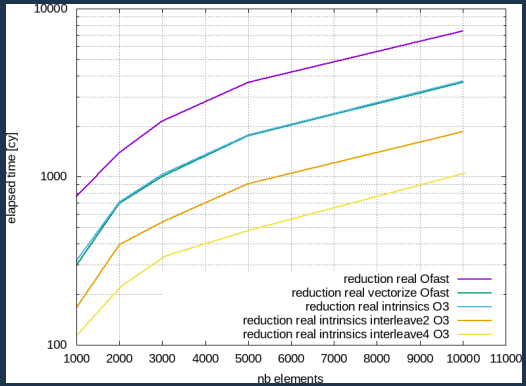


Elapsed Time per element (cy/el)

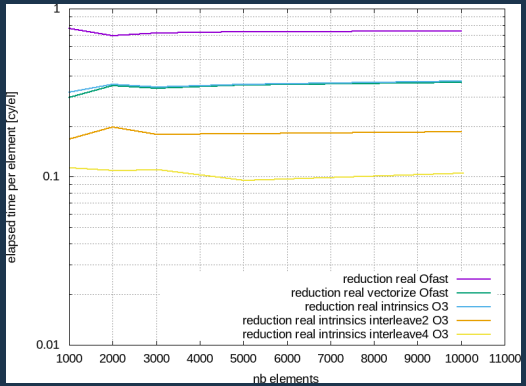


The reduction : intrinsics interleaved 4

Total Elapsed Time (cy)

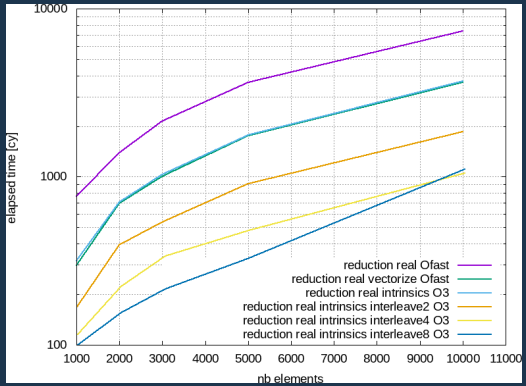


Elapsed Time per element (cy/el)

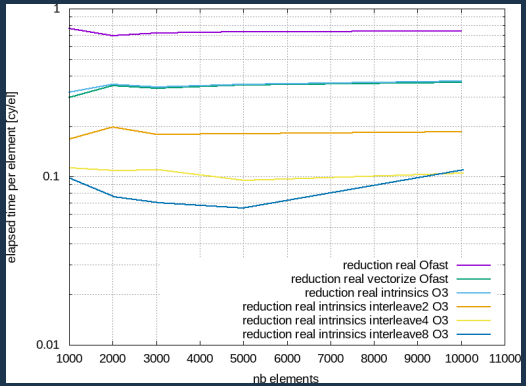


The reduction : intrinsics interleaved 8

Total Elapsed Time (cy)

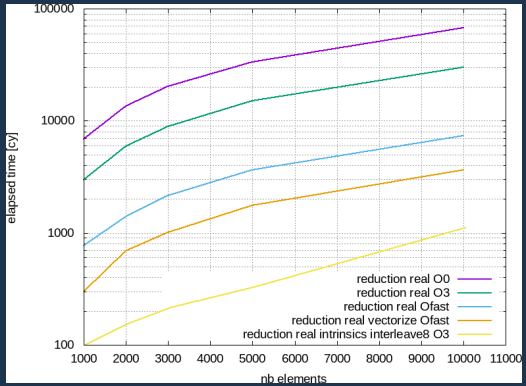


Elapsed Time per element (cy/el)

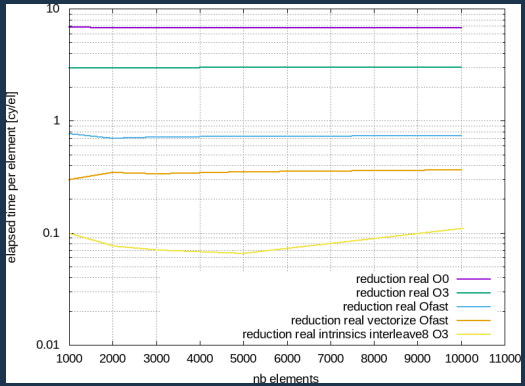


The reduction : summary

Total Elapsed Time (cy)



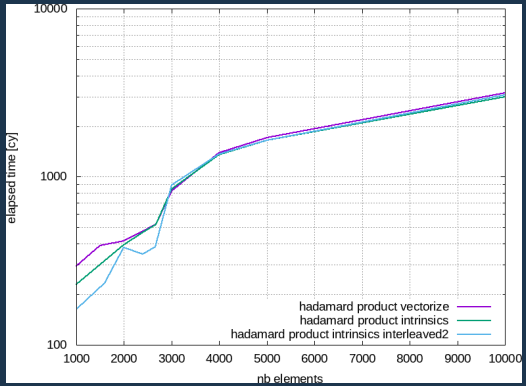
Elapsed Time per element (cy/el)



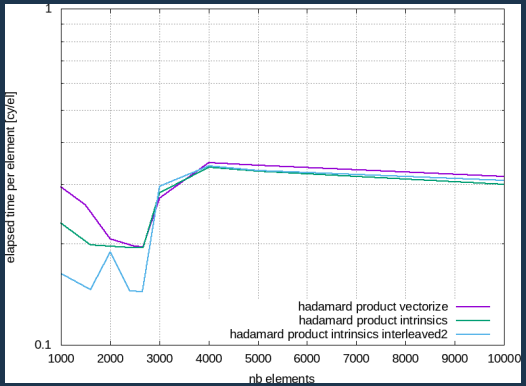
5000 elements, Intrinsics is **166** times faster than -**O0** and 7 times faster than -**Ofast** vectorized

What about the Hadamard product ?

Total Elapsed Time (cy)

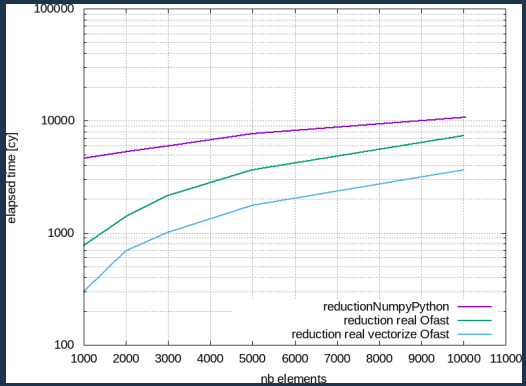


Elapsed Time per element (cy/el)

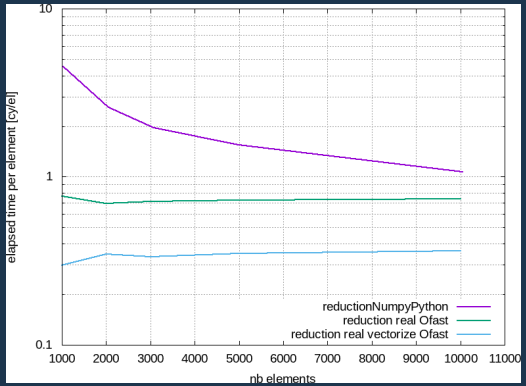


The reduction : Python

Total Elapsed Time (cy)



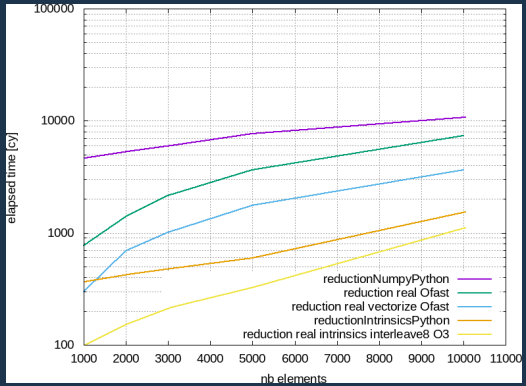
Elapsed Time per element (cy/el)



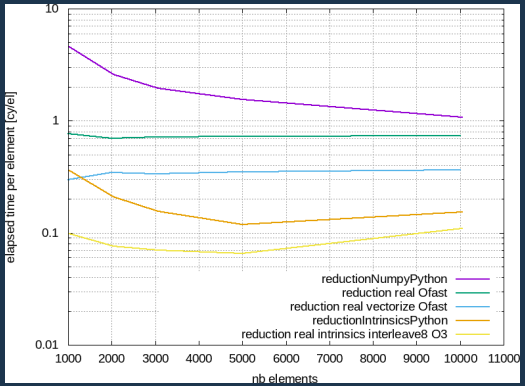
1000 elements, GCC vectorized version is **13** times faster than **numpy** sum

The reduction : Python Summary

Total Elapsed Time (cy)



Elapsed Time per element (cy/el)



1000 elements, our python reduction is **10** times faster than **numpy** sum